A steel rod 1600 mm long and 12 mm diameter is bent into the shape shown on the diagram. The density of steel is $7800 \mathrm{~kg} / \mathrm{m}^{3}$. The co-ordinates of the corners are given in the table below (in mm ).

| Point | x co-ordinate y co-ordinate | z co-ordinate |  |  |
| :--- | :--- | :--- | :--- | :--- |
| O | 0 | 0 | 0 |  |

a) Calculate $\mathrm{I}_{\mathrm{xx}}, \mathrm{I}_{\mathrm{yy}}, \mathrm{I}_{\mathrm{zz}}$, the moments of inertia of this object about the x , y and z axes respectively.
b) Supports are present at at O and A which allow the bent rod to rotate freely about the z axis and a torque of 1 Nm is applied to leg OA. Compute the angular acceleration of the object about the z axis and the reactions at O and A .
c) If the torque is sustained on the bent rod until it has rotated through exactly 10 full cycles, calculate the reaction forces at O and A at that instant.

## SOLUTION

If there is a shorter way to find the moments of inertia and centre of gravity, then b) and c) are quite easy.
The moment of inertia of a uniform rod of length $L$ is:
About the end $\quad \rho \mathrm{AL}^{3} / 3$
About the middle $\quad \rho \mathrm{AL}^{3} / 12$
The parallel axis theorem also gives $\mathrm{I}=\left\{\mathrm{I}_{\mathrm{g}}+\mathrm{M} \mathrm{k}{ }^{2}\right\}$ where k is the radius to the centre of gravity.
If $\mathrm{I}_{\mathrm{g}}=\mathrm{ML}^{2} / 12$ then $\mathrm{I}=\rho \mathrm{AL}\left\{\mathrm{L}^{2} / 12+\mathrm{k}^{2}\right\}$
$\rho \mathrm{A}=7800 \times \pi \times 0.12^{2} / 4=0.8822 \mathrm{~kg} / \mathrm{m}$
There may be a more systematic way to calculate the moment of inertia but it seems that we need to work out $\mathrm{I}_{\mathrm{xx}}$, $I_{y y}$ and $I_{z z}$ for each of the 6 legs - a lot of time needed.

SECTION OA L=0.4
$\mathrm{I}_{\mathrm{xx}}=\frac{\rho \mathrm{AL}^{3}}{3}=0.8822\left(\frac{0.4^{3}}{3}\right)=0.018819 \mathrm{~kg} \mathrm{~m}^{2}$

$\mathrm{I}_{\mathrm{yy}}=\mathrm{I}_{\mathrm{xx}}=0.18819 \mathrm{~kg} \mathrm{~m}^{2} \quad \mathrm{I}_{\mathrm{zz}}=0$

## SECTION AB

$\mathrm{I}_{\mathrm{xx}}=\operatorname{\rho AL}\left\{0.4^{2}\right\}=0.8822(0.2)\left\{0.4^{2}\right\}=0.028229 \mathrm{~kg} \mathrm{~m}^{2}$
$I_{y y}=\rho A L\left\{\frac{L^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.2)\left\{\frac{0.2^{2}}{12}+\left(0.4^{2}+0.1^{2}\right)\right\}=0.03058 \mathrm{~kg} \mathrm{~m}^{2}$
$I_{z z}=\frac{\rho A L^{3}}{3}=0.8822\left(\frac{0.2^{3}}{3}\right)=0.002352 \mathrm{~kg} \mathrm{~m}^{2}$

## SECTION BC

$\mathrm{I}_{\mathrm{xx}}=\rho A L\left\{\frac{\mathrm{~L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.3)\left\{\frac{0.3^{2}}{12}+\left(0.4^{2}+0.15^{2}\right)\right\}=0.050283 \mathrm{~kg} \mathrm{~m}^{2}$
$\mathrm{I}_{\mathrm{yy}}=\mathrm{Mk}^{2}=0.8822(0.3)\left(0.2^{2}+0.4^{2}\right)=0.050283 \mathrm{~kg} \mathrm{~m}^{2}$
$\mathrm{I}_{\mathrm{zz}}=\rho \mathrm{AL}\left\{\frac{\mathrm{L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.3)\left\{\frac{0.3^{2}}{12}+\left(0.2^{2}+0.15^{2}\right)\right\}=0.018525 \mathrm{~kg} \mathrm{~m}^{2}$

## SECTION CD

$\mathrm{I}_{\mathrm{xx}}=\mathrm{Mk}^{2}=0.8822(0.2)\left(0.3^{2}+0.4^{2}\right)=0.041108 \mathrm{~kg} \mathrm{~m}^{2}$
$\mathrm{I}_{\mathrm{yy}}=\rho \mathrm{AL}\left\{\frac{\mathrm{L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.2)\left\{\frac{0.2^{2}}{12}+\left(0.4^{2}+0.3^{2}\right)\right\}=0.044696 \mathrm{~kg} \mathrm{~m}^{2}$
$\mathrm{I}_{\mathrm{zz}}=\rho \mathrm{AL}\left\{\frac{\mathrm{L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.2)\left\{\frac{0.2^{2}}{12}+\left(0.3^{2}+0.3^{2}\right)\right\}=0.032347 \mathrm{~kg} \mathrm{~m}^{2}$

## SECTION DE

$\mathrm{I}_{\mathrm{xx}}=\rho \mathrm{AL}\left\{\frac{\mathrm{L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.3)\left\{\frac{0.3^{2}}{12}+\left(0.4^{2}+0.15^{2}\right)\right\}=0.050283 \mathrm{~kg} \mathrm{~m}^{2}$
$I_{y y}=\rho A \int_{0}^{0.3} r^{2} d y \quad r^{2}=0.4^{2}+0.4^{2}=0.32 I_{y y}=0.8822 \int_{0}^{0.3}(0.32) \mathrm{dy}=0.8822[0.32 y]_{0}^{0.3}=0.084687 \mathrm{~kg} \mathrm{~m}^{2}$
$\mathrm{I}_{\mathrm{zz}}=\rho \mathrm{AL}\left\{\frac{\mathrm{L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.3)\left\{\frac{0.3^{2}}{12}+\left(0.4^{2}+0.15^{2}\right)\right\}=0.050283 \mathrm{~kg} \mathrm{~m}^{2}$

## SECTION EF

$\mathrm{I}_{\mathrm{xx}}=\rho \mathrm{AL}\left\{\frac{\mathrm{L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.2)\left\{\frac{0.2^{2}}{12}+\left(0.5^{2}\right)\right\}=0.044696 \mathrm{~kg} \mathrm{~m}^{2}$
$\mathrm{I}_{\mathrm{yy}}=\rho A L\left\{\frac{\mathrm{~L}^{2}}{12}+\mathrm{k}^{2}\right\}=0.8822(0.2)\left\{\frac{0.2^{2}}{12}+\left(0.5^{2}+0.4^{2}\right)\right\}=0.072928 \mathrm{~kg} \mathrm{~m}^{2}$
$\mathrm{I}_{\mathrm{zz}}=\rho A L \mathrm{k}^{2}=0.8822(0.2)(0.4)^{2}=0.0282291 \mathrm{~kg} \mathrm{~m}^{2}$

## TOTALS

|  |  | $\mathrm{I}_{\mathrm{xx}}$ | $\mathrm{I}_{\mathrm{yy}}$ |
| :--- | :--- | :--- | :--- |
| OA | 0.18819 | 0.18819 | $\mathrm{I}_{\mathrm{zz}}$ |
| AB | 0.02822 | 0.03058 | 0.00235 |
| BC | 0.05028 | 0.05028 | 0.01852 |
| CD | 0.04410 | 0.04469 | 0.03234 |
| DE | 0.05028 | 0.08468 | 0.05028 |
| EF | 0.04469 | 0.07292 | 0.02823 |
| TOTAL | 0.40576 | 0.04713 | 0.13172 |

There is much scope for error in arriving at these figures.

Part (b) $\quad$ Angular acceleration $=\alpha=\mathrm{T} / \mathrm{I}_{\mathrm{zz}}=1 / 0.13172=7.6 \mathrm{rad} / \mathrm{s}^{2}$
The centre of gravity is required and this requires another lengthy calculation. We need to find the centre of gravity in each plane.
In the z direction ( r is the radius to the centre of each leg in the z direction)

| Section | r | length L | mass $=\rho A L$ | m r |
| :--- | :--- | :--- | :--- | :--- |
| OA | 0.2 | 0.4 | 0.35286 | 0.070572 |
| AB | 0.4 | 0.2 | 0.17643 | 0.070572 |
| BC | 0.4 | 0.3 | 0.26464 | 0.105856 |
| CD | 0.4 | 0.2 | 0.17643 | 0.0 .070572 |
| DE | 0.4 | 0.3 | 0.26464 | 0.105856 |
| EF | 0.5 | 0.2 | 0.17643 | 0.088215 |
| Totals |  |  | 1.41143 | 0.511643 |

Check total mass $=1.6 \rho \mathrm{~A}=1.4115$
The centre of gravity is $\overline{\mathrm{z}}=0.511643 / 1.41143=0.3625 \mathrm{~m}$
In the x direction ( r is the radius to the centre of each leg in the x direction)

| Section | r | length L | mass $=\rho \mathrm{AL}$ | mr |
| :--- | :--- | :--- | :--- | :--- |
| OA | 0 | 0.4 | 0.35286 | 0 |
| AB | 0.1 | 0.2 | 0.17643 | 0.017643 |
| BC | 0.2 | 0.3 | 0.26464 | 0.052928 |
| CD | 0.3 | 0.2 | 0.17643 | 0.052928 |
| DE | 0.4 | 0.3 | 0.26464 | 0.105856 |
| EF | 0.4 | 0.2 | 0.17643 | 0.070572 |
| Totals |  |  | 1.41143 | 0.3 |

The centre of gravity is $\overline{\mathrm{x}}=0.3 / 1.41143=0.2126 \mathrm{~m}$
In the $y$ direction ( $r$ is the radius to the centre of each leg in the $y$ direction)

| Section | r | mass $=\rho A L$ | m r |
| :--- | :--- | :--- | :--- |
| OA | 0 | 0.35286 | 0 |
| AB | 0 | 0.17643 | 0 |
| BC | 0.15 | 0.26464 | 0.039696 |
| CD | 0.3 | 0.17643 | 0.052928 |
| DE | 0.15 | 0.26464 | 0.039696 |
| EF | 0 | 0.17643 | 0 |
| Totals |  | 1.41143 | 0.13232 |

The centre of gravity is $\bar{y}=0.13232 / 1.41143=0.0937 \mathrm{~m}$
The centre of gravity of the mass rotating about the z axis is at radius R as shown. $\mathrm{R}=\left(0.2126^{2}+0.0937^{2}\right)^{1 / 2}=0.2323$



At the instant the torque is applied the angular velocity is zero so no centrifugal force is produced. If the body is free to rotate it will rest with the centre of gravity vertically below the zaxis. Only the weight of the body acting at the centre of gravity need be considered. Taking moments about ' O ' we have:
$\mathrm{Mg}(0.3625)=\mathrm{R}_{\mathrm{A}}(0.4)$
$(1.4115)(9.81)(0.3625)=R_{A}(0.4)$
$13.8468(0.3625)=\mathrm{R}_{\mathrm{A}}(0.4)$
$\mathrm{R}_{\mathrm{A}}=12.586 \mathrm{~N}$
$\mathrm{R}_{\mathrm{O}}=13.8468-12.586=1.298$
I am not sure if this is what the examiner wants or whether weight is ignored in this problem.
Part (c)
After 10 revolutions an angular velocity $\omega$ is attained.
The centrifugal force is $\mathrm{M} \omega^{2} \mathrm{R}=1.4115 \omega^{2} 0.2323=0.3279 \omega^{2}$
Angle rotated $=\theta=10 \times 2 \pi$ radian
$\omega^{2}=(2 \alpha \theta)=(2)(7.6)(20 \pi)=955 \mathrm{~N}$
Ignoring the weight and again taking moments about ' O ' we have:
$(955)(0.3625)=R_{\mathrm{A}}(0.4)$
$\mathrm{R}_{\mathrm{A}}=865.5 \mathrm{~N}$
$\mathrm{R}_{\mathrm{O}}=955-865.5=89.5 \mathrm{~N}$

